

SCALING PROPERTIES OF SMALL-SCALE FLUCTUATIONS IN MAGNETOHYDRODYNAMIC TURBULENCE

JEAN CARLOS PEREZ¹, JOANNE MASON², STANISLAV BOLDYREV^{3,4}, FAUSTO CATTANEO⁵

¹Space Science Center, University of New Hampshire, Durham, NH 03824

²College of Engineering, Mathematics and Physical Sciences, University of Exeter, EX4 4QF, UK

³Department of Physics, University of Wisconsin at Madison, 1150 University Ave, Madison, WI 53706

⁴Kavli Institute for Theoretical Physics, University of California at Santa Barbara, Santa Barbara, CA 93106

⁵Department of Astronomy and Astrophysics, University of Chicago, 5640 S. Ellis Ave, Chicago, IL 60637
 jeanc.perez@unh.edu, j.mason@exeter.ac.uk, boldyrev@wisc.edu, cattaneo@flash.uchicago.edu

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ABSTRACT

Magnetohydrodynamic (MHD) turbulence in the majority of natural systems, including the interstellar medium, the solar corona, and the solar wind, has Reynolds numbers far exceeding the Reynolds numbers achievable in numerical experiments. Much attention is therefore drawn to the universal scaling properties of small-scale fluctuations, which can be reliably measured in the simulations and then extrapolated to astrophysical scales. However, in contrast with hydrodynamic turbulence, where the universal structure of the inertial and dissipation intervals is described by the Kolmogorov self-similarity, the scaling for MHD turbulence cannot be established based solely on dimensional arguments due to the presence of an intrinsic velocity scale – the Alfvén velocity. In this Letter, we demonstrate that the Kolmogorov first self-similarity hypothesis cannot be formulated for MHD turbulence in the same way it is formulated for the hydrodynamic case. Besides profound consequences for the analytical consideration, this also imposes stringent conditions on numerical studies of MHD turbulence. In contrast with the hydrodynamic case, the discretization scale in numerical simulations of MHD turbulence should decrease faster than the dissipation scale, in order for the simulations to remain resolved as the Reynolds number increases.

Subject headings: magnetic fields, – magnetohydrodynamics (MHD), – turbulence

1. INTRODUCTION

The energy distribution over scales in magnetic plasma turbulence is the important input ingredient in theories of the interstellar medium (Elmegreen & Scalo 2004; Brandenburg & Nordlund 2011), scintillation of galactic radio sources (Goldreich & Sridhar 2006; Coles et al. 2010), particle heating and acceleration by magnetic plasma fluctuations in the solar wind (Chandran et al. 2010, 2011). At scales much larger than the plasma micro-scales (such as the ion gyroscale and the ion inertial length) many fundamental aspects of the plasma dynamics can be captured in the framework of MHD (e.g., Biskamp 2003; Terry & Tangri 2009; Tobias et al. 2013), which can be effectively studied both analytically and numerically.

In spite of advances in present-day computer simulations, the Reynolds numbers of astrophysical flows ($Re \sim 10^6$ – 10^{16}) exceed by many orders of magnitude the Reynolds numbers achieved numerically ($Re \sim 10^4$). In this situation, major interest is attracted to the scaling properties of MHD turbulence, which can be reliably established from numerical simulations. Such an approach motivates phenomenological models that can be extrapolated to astrophysically relevant scales. Examples include models of astrophysical dynamo action (e.g., Malyskin & Boldyrev 2010; Brandenburg et al. 2012; Kolekar et al. 2012), models of magnetic reconnection at high Lundquist numbers in the solar wind and the solar corona (e.g., Longcope & Sudan 1994; Rappazzo et al. 2008; Ng et al. 2012; Zhdankin et al. 2013), and studies of turbulent mixing in the interstellar medium (e.g.,

Sur et al. 2014), etc.

The basic assumptions of universality and scale invariance that are common in studies of hydrodynamic turbulence are not well-justified and, as a result, not well-understood in the MHD case, and they require careful investigation. In the hydrodynamic case, the Kolmogorov first self-similarity hypothesis implies that at scales much smaller than the driving scale, the energy spectrum of incompressible non-magnetized fluid turbulence has a universal form (Kolmogorov 1941; Obukhov 1941):

$$E(k) = C_k \epsilon^{2/3} k^{-5/3} g_h(k\eta_h), \quad (1)$$

where ϵ is the mean energy dissipation rate,

$$\eta_h = \nu^{3/4} \epsilon^{-1/4} \quad (2)$$

is the Kolmogorov viscous scale, and ν is the fluid viscosity. The function $g_h(x)$ is expected to be universal, that is, independent of the nature of the large-scale driving, and to satisfy $g_h(0) = 1$. With the driving applied at scale L , in the inertial interval of turbulence $kL \gg 1 \gg k\eta_h$ the function $g_h(x) \rightarrow 1$ as $\eta_h \rightarrow 0$, thus leading to the well-known $k^{-5/3}$ Kolmogorov's inertial range spectrum. At the dissipation scales, $k\eta_h \gtrsim 1$, the form of the function g_h cannot be derived from scaling arguments. However, it has been constrained by detailed experimental and numerical measurements (e.g., Tsuji 2004; Donzis & Sreenivasan 2010) and phenomenologically modeled (e.g., Monin & Iaglom 1975).

In MHD turbulence the Kolmogorov self-similarity relation (1) does not apply due to the presence of the Alfvén velocity $v_A = B_0/\sqrt{4\pi\rho}$ associated with the

large-scale magnetic field B_0 . The large-scale magnetic field mediates the turbulent dynamics at small scales, therefore, the energy spectrum may essentially depend on the large scale (Iroshnikov 1963; Kraichnan 1965; Goldreich & Sridhar 1995; Ng & Bhattacharjee 1996; Galtier et al. 2000; Bhattacharjee & Ng 2001; Boldyrev 2005, 2006). In this case, the general form of the energy spectrum can be written as

$$E(k) = C_k^M \epsilon^{2/3} k^{-5/3} g(k\eta, k\Lambda), \quad (3)$$

where η is the dissipation scale and $\Lambda \sim L$ is the scale parameter related to the large-scale organization of the flow – both can be different in different setups. The mediation of the small-scale interaction by the large-scale magnetic field implies that in the inertial interval, $k\eta \ll 1$, one cannot require that $g(0, k\Lambda) = 1$. Rather, in order to establish the energy spectrum in this case one needs to study the nonlinear interaction of Alfvén wave packets in detail (Iroshnikov 1963; Kraichnan 1965; Goldreich & Sridhar 1995; Ng & Bhattacharjee 1996; Galtier et al. 2000; Bhattacharjee & Ng 2001; Boldyrev 2005, 2006).

2. SELF-SIMILARITY IN WEAK AND STRONG MHD TURBULENCE.

We start with the case of balanced weak MHD turbulence, where the average energies in oppositely propagating Alfvén wave packets are the same. We assume a strong uniform background field, $B_0 \gg b_{\text{rms}}$, and suppose that turbulence is isotropically excited at scale L , such that $v_{\text{rms}} \sim b_{\text{rms}}/\sqrt{4\pi\rho}$. The weakness of the interaction follows from the fact that the linear Alfvén frequency, v_A/L , is much larger than the frequency of nonlinear interaction, v_{rms}/L . It has been derived that the inertial-interval energy spectrum of balanced MHD turbulence scales with the field-perpendicular wavenumber as k_{\perp}^{-2} (e.g., Galtier et al. 2000; Boldyrev & Perez 2009; Wang et al. 2011), which allows us to write the asymptotics of the spectral function in the form

$$g_w(0, k_{\perp}\Lambda) \sim (k_{\perp}\Lambda)^{-1/3}. \quad (4)$$

One can demonstrate that $\Lambda \sim L$, and $\eta_w = \nu(v_A/\epsilon\Lambda)^{1/2}$. Thus, we observe that the inertial interval essentially depends on the outer scale.

A similar consideration applies in the regime of steadily driven balanced strong MHD turbulence. It has been found in numerical simulations and phenomenological models that the field-perpendicular energy spectrum in this case scales as $k_{\perp}^{-3/2}$ (Müller & Grappin 2005; Maron & Goldreich 2001; Haugen et al. 2004; Boldyrev 2005, 2006; Chen et al. 2011; Mason et al. 2008; Perez et al. 2012), which implies the following asymptotic for the spectral function:

$$g_s(0, k_{\perp}\Lambda) \sim (k_{\perp}\Lambda)^{1/6}. \quad (5)$$

Here Λ is related to the cross-helicity of the flow (for example, $\Lambda \sim L$, if the magnetic and velocity fluctuations are driven at the outer scale in a non-correlated fashion), and

$$\eta_s = \nu^{2/3} \Lambda^{1/9} \epsilon^{-2/9} \quad (6)$$

is the dissipation scale, see, e.g., (Perez et al. 2012). In the imbalanced case it has also been shown that

the asymptotic of the spectrum follows Equation (4) in the weak imbalanced case (Boldyrev & Perez 2009) and Equation (5) in the strong imbalanced case (Perez & Boldyrev 2009; Podesta & Bhattacharjee 2010).

Both examples demonstrate that the dependence on Λ in MHD turbulence is crucial for establishing the energy distribution in both the inertial and dissipation intervals. In both cases the spectrum deviates from the Kolmogorov $k^{-5/3}$ due to a reduction of the nonlinear interaction by a certain mechanism related to the large-scale magnetic field. In the case of weak turbulence, such a mechanism is the decorrelation of the triple-field products due to the short crossing time of counter-propagating Alfvén waves (e.g., Ng & Bhattacharjee 1996; Galtier et al. 2000; Bhattacharjee & Ng 2001). In the case of strong turbulence, a weakening of the nonlinear interaction is provided by the scale-dependent angular alignment between magnetic and velocity fluctuations, that is, progressive “Alfvénization” of the turbulence at small scales (e.g., Boldyrev 2005, 2006; Mason et al. 2008). As we argue in the next section, the dependence of the spectral function $g_s(k\eta, k\Lambda)$ on the outer scale is crucial for the applicability of discrete numerical schemes for simulations of MHD turbulence.

3. THE PROBLEM OF NUMERICAL RESOLUTION IN SIMULATIONS OF MHD TURBULENCE.

In this section we concentrate on strong MHD turbulence, and assume that the simulations are performed in a numerical scheme discretized at scale Δ , which can be the grid size of a finite-difference scheme, the inverse dealiasing cut-off of a pseudo-spectral scheme, etc. In the presence of a numerical cutoff Δ , the general form of the function g_s is $g_s(k\eta, k\Lambda, k\Delta)$. The solution of the discrete scheme in general is different from the physical solution and it may have different scaling properties as it contains an additional dimensional parameter Δ . However, it needs to converge to the physical solution as $\Delta \rightarrow 0$.

It should be recalled that in the hydrodynamic case, when the spectrum is independent of Λ , the g function can be written as $g_h(k\eta_h, \Delta/\eta_h)$. Therefore, as long as the numerical resolution is a fixed fraction of the dissipation scale $\Delta/\eta_h = \text{const}$, the form of the function $g_h(k\eta_h)$ is universal (e.g., Gotoh 2002). In contrast, the presence of an additional scale Λ in the MHD case means that there are infinitely many g_s functions that provide the same inertial interval asymptotics, but have different behavior at the subrange scales. Consider, for example, a spectral function¹

$$g_s = \left[\frac{1}{k\Lambda} + \frac{\Delta}{\sqrt{\eta_s}\Lambda} \right]^{-1/6} g_1(k\eta_s, k\Delta), \quad (7)$$

where $g_1(0, 0) = 1$. The expression (7) agrees with the inertial scaling of $-3/2$, while it steepens at small scales due to the finite discretization cutoff Δ . In this example, the scaling of the numerically measured energy spectrum changes at scale $k \sim \sqrt{\eta_s/\Lambda}(1/\Delta)$ from $-3/2$ to $-5/3$; however, this spectral steepening represents the

¹ This function is given for illustrative purposes and is not chosen to match a particular numerical simulation.

property of the numerical scheme, not of the physical solution. In order to avoid the influence of numerical effects, one needs to ensure that the discretization cutoff is sufficiently small. For instance, in order to observe the inertial interval up to the dissipation scale $k \sim 1/\eta_s$, one needs to require that $\Delta < \eta_s^{3/2}/\Lambda^{1/2}$.

In this example the discretization scale in the numerical simulations needs to decrease faster than the dissipation scale, for the simulations to be resolved. In the next section we demonstrate that a similar situation is encountered in simulations of MHD turbulence.

4. NUMERICAL SIMULATIONS.

The incompressible MHD equations can be written in the Elsässer form:

$$\left(\frac{\partial}{\partial t} \mp \mathbf{v}_A \cdot \nabla\right) \mathbf{z}^\pm + (\mathbf{z}^\mp \cdot \nabla) \mathbf{z}^\pm = -\nabla P + \nu \nabla^2 \mathbf{z}^\pm + \mathbf{f}^\pm, \\ \nabla \cdot \mathbf{z}^\pm = 0, \quad (8)$$

where $\mathbf{z}^\pm = \mathbf{v} \pm \mathbf{b}$ are the Elsässer variables, and \mathbf{v} and \mathbf{b} are the fluctuating velocity and magnetic fields in units of the Alfvén velocity, $\mathbf{v}_A = \mathbf{B}_0/\sqrt{4\pi\rho_0}$. In these equations $P = (p/\rho_0 + b^2/2)$, where p is the plasma pressure, ρ_0 is the background plasma density and ν is the fluid viscosity. For simplicity, the viscosity is equal to the magnetic diffusivity. The turbulence is driven at large scales by the forces \mathbf{f}^\pm . In the linear case, the plasma waves can be decomposed into shear Alfvén waves whose polarizations are perpendicular to both \mathbf{B}_0 and the wave-vector \mathbf{k} , and pseudo-Alfvén waves whose polarizations are in the plane of \mathbf{B}_0 and \mathbf{k} and perpendicular to \mathbf{k} .

In the case of strong MHD turbulence, the pseudo-Alfvén modes are dynamically irrelevant for the turbulent cascade (e.g., Goldreich & Sridhar 1995). One can therefore filter out the pseudo-Alfvén modes by setting $\mathbf{z}_\parallel^\pm = 0$, which reduces the equations to the Reduced MHD model:

$$\left(\frac{\partial}{\partial t} \mp \mathbf{v}_A \cdot \nabla_\parallel\right) \mathbf{z}_\perp^\pm + (\mathbf{z}_\perp^\mp \cdot \nabla_\perp) \mathbf{z}_\perp^\pm = -\nabla_\perp P \\ + \nu \nabla^2 \mathbf{z}_\perp^\pm + \mathbf{f}_\perp^\pm. \quad (9)$$

We note that in RMHD the fluctuating fields have only two vector components, but that each depends on all three spatial coordinates. Due to incompressibility, each field has only one degree of freedom, which can be expressed in terms of stream functions in the more standard form of the RMHD equations (Strauss 1976). The equivalence between RMHD and MHD in the strong turbulence regime has been shown in numerical simulations; for an extensive discussion see Mason et al. (2012). In light of this equivalence, we will refer to the numerical spectrum obtained from RMHD simulations as the MHD spectrum. We solve the RMHD equations (9) in a periodic, rectangular domain with aspect ratio $L_\perp^2 \times L_\parallel$, where the subscripts denote the directions perpendicular and parallel to \mathbf{B}_0 , respectively. We set $L_\perp = 2\pi$, $L_\parallel/L_\perp = 6$ and $\mathbf{B}_0 = 5\mathbf{e}_z$. A fully dealiased three-dimensional pseudo-spectral algorithm is used on a grid with a resolution of $N_\perp^2 \times N_\parallel$ mesh points.

Both Elsässer variables are driven by independent random forces \mathbf{f}^+ and \mathbf{f}^- applied in Fourier space at wavenumbers $2\pi/L_\perp \leq k_{x,y} \leq 2(2\pi/L_\perp)$, $k_\parallel = 2\pi/L_\parallel$. The

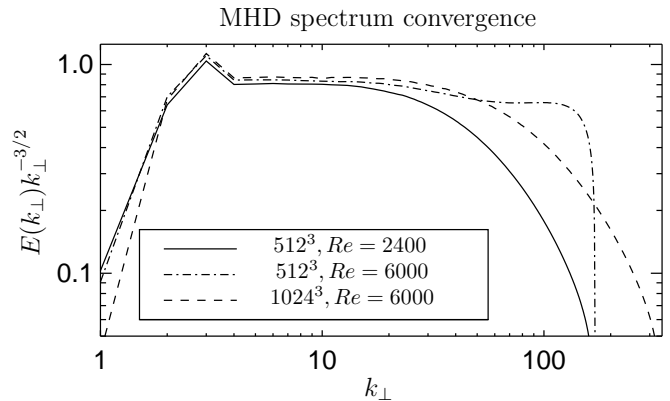


FIG. 1.— Resolution study of the numerical spectrum in MHD turbulence. The solid line represents the energy spectrum in numerical simulations of MHD turbulence at 512^3 collocation points and $Re = 2400$. The inertial interval is well-resolved in this case. The dash-dotted line represents a similar run where the Reynolds number is increased to $Re = 6000$. The latter simulation is unresolved; as a result, the numerical solution does not approximate the physical one at small scales. The numerical spectrum steepens at $k \geq 15$, and then flattens closer to the cut-off scale, which is a purely numerical effect. This numerical effect disappears as the resolution is increased to 1024^3 without changing the physical parameters of the simulations (the dashed curve), where the inertial interval now extends to about $k \sim 25$.

forces have no component along z and they are solenoidal in the xy plane. Their Fourier coefficients are Gaussian random numbers with amplitudes chosen so that $v_{\text{rms}} \sim 1$. The individual random values are refreshed independently on average approximately 10 times per turnover time of the large-scale eddies. The variances $\sigma_\pm^2 = \langle |\mathbf{f}^\pm|^2 \rangle$ control the average rates of energy injection into the z^+ and z^- fields. In this work we discuss the regime of balanced MHD turbulence, i.e., $\sigma^+ \approx \sigma^-$. The Reynolds number is defined as $Re = v_{\text{rms}}(L/2\pi)/\nu$.

5. THE RESULTS.

The spectra of MHD turbulence obtained in the simulations are shown in Figure 1. The solid line represents the energy spectrum for a 512^3 , $Re = 2400$ run, which is well-resolved. The dash-dotted line shows the same set up with decreased viscosity, which makes the dissipation scale approach the numerical cut-off. The scales at $k > 15$ are now significantly affected by the proximity to the dealiasing cut-off (cf. Perez et al. 2012). The proximity to the k -space cutoff is known to distort the spectral behavior at small scales in hydrodynamic simulations (e.g., Cichowlas et al. 2005; Frisch et al. 2008; Connaughton 2009; Grappin & Müller 2010); our MHD runs bear similarity with those results. Such a spectral distortion is a property of the numerical scheme and it should not be confused with the inertial interval behavior. Indeed, as one increases the number of grid points to 1024^3 (thereby reducing Δ to $\Delta/2$), while keeping all the physical parameters unchanged, the numerical distortion disappears, see the dashed line in Figure 1.

We now note that in the resolved runs, the dissipation interval scales according to the formula (6), see Figure 2, and also (Perez et al. 2012). However, in the unresolved runs, the scaling of the small-scale spectrum is different and is consistent with expression (2), as is seen in Figure 3. This is not surprising; as was discussed in the previous section, the scaling of the numerical solution close to the discretization cutoff may be different from

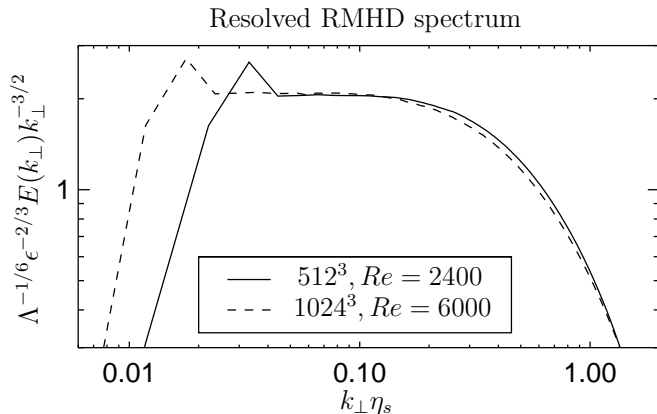


FIG. 2.— This figure illustrates the scaling of a fully resolved numerical spectrum. The solid curve corresponds to a resolution of 512^3 and $Re = 2400$, the dashed curve corresponds to a resolution 1024^3 and $Re = 6000$. In both runs $\Delta/\eta_s \approx 0.17 \ll 1$, so that both simulations are resolved at small scales. Here, $\Delta = L_{\perp}/N_{\perp}$. As a result, the solution of the numerical scheme is self-similar with $g_s(0, k_{\perp} \Lambda)$ given by Equation (5).

the scaling of the physical solution if the former does not approximate the latter. Such a scaling of unresolved runs was previously observed in (Beresnyak 2011, 2012, 2014), where it was incorrectly attributed to the scaling of the physical solution because the numerical convergence was not checked.

6. DISCUSSION.

The presented results reveal an important property of the dissipation interval of MHD turbulence. As we have seen, two scales play a role here: the physical dissipation scale, η_s , given by (6), and the scale, η_h , given by (2). Suppose that the discretization scale, Δ , in numerical simulations is decreased proportionally to η_s as the Reynolds number increases. Then, since η_h decreases faster, at some Reynolds number we will have $\Delta \sim \eta_h$ and the simulations will become unresolved. In this case, the numerical scheme will not approximate the physical solution at scales close to η_h . If starting from this point, Δ starts to decrease proportionally to η_h , the spectral distortion will be preserved, and the approximation will not improve (cf. Fig 3). However, if Δ continues to decrease slower than η_h , the approximation of the numerical scheme will continue to degrade. We therefore conclude that in order to resolve the dissipation interval of MHD turbulence, the discretization of the numerical scheme should satisfy $\Delta \ll \eta_h$, and it should decrease at least as fast as η_h to maintain the same level of approximation.

The physical explanation of the observed phenomenon is the following. As proposed in (Boldyrev 2005, 2006), the $-3/2$ scaling of the inertial interval of MHD turbulence is related to the scale-dependent dynamic alignment between magnetic and velocity fluctuations, where the alignment angle decreases with the scale approximately as $\theta(r) \propto r^{1/4}$. Numerical simulations demonstrate that such alignment is present not only in the inertial interval but also in the dissipation range as long as we do not approach the numerical cut-off too closely (Mason et al. 2008; Perez et al. 2012). This alignment leads to the scale-dependent weakening of the nonlinear interaction, changing the naive $-5/3$ scaling of the equation to the observed $-3/2$ scaling of the solution.

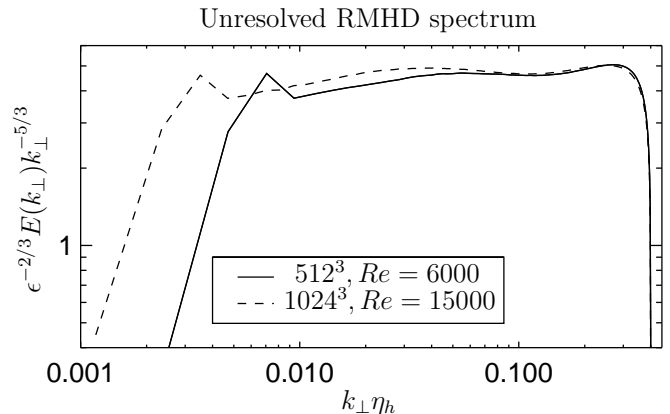


FIG. 3.— This figure illustrates the scaling of the unresolved numerical spectrum. The solid curve corresponds to a resolution of 512^3 and $Re = 6000$, the dashed curve corresponds to a resolution 1024^3 and $Re = 15,000$. The Re numbers are chosen as to ensure that $\Delta/\eta_h \approx 0.83$ is the same in both runs. Both simulations are essentially unresolved at small scales. As a result, at $k\eta_h \gtrsim 0.1$ the solution of the numerical scheme scales differently from the inertial interval.

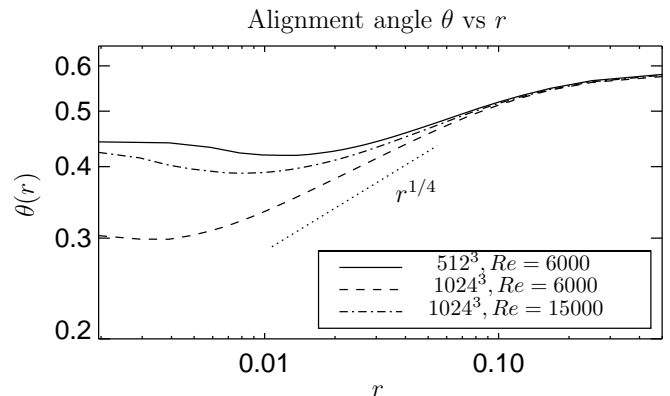


FIG. 4.— Scaling of the alignment angle $\theta(r)$ between the velocity and magnetic fluctuations measured at scale r (the numerical procedure for the measurements is described in detail in (Perez et al. 2012)). In a resolved run exhibiting the $-3/2$ scaling, the alignment $\theta(r) \sim r^{1/4}$ is well-preserved down to the scale $r \sim 0.005$ (the dashed curve). However, in the unresolved runs the alignment is already significantly spoiled at scale $r \sim 0.05$, where the curves start to deviate from the $r^{1/4}$ scaling and flatten at smaller scales (the solid and dash-dotted curves). The absence of the scale-dependent alignment leads to the $-5/3$ scaling at these scales, as observed in Figure 3.

In the unresolved intervals, however, the correlation between magnetic and velocity fluctuations gets destroyed due to the proximity to the dealiasing cut-off. A similar behavior has been documented in numerical simulations of hydrodynamic turbulence, where an abrupt cutoff in the k space led to unphysical distortion of the energy spectrum (Cichowlas et al. 2005; Frisch et al. 2008; Connaughton 2009; Grappin & Müller 2010). In the extreme case, when the explicit dissipation was totally absent, the spectral cutoff would lead to an energy pile up and mode thermalization close to the cutoff scale. At such scales any spatial correlation of fluctuations existing in the turbulent flow would be lost.

It is reasonable to propose that a similar tendency exists in MHD turbulence when the physical dissipation is not strong enough in the vicinity of the numerical cutoff. This leads to the unphysical numerical distur-

tion seen in Figure 3 and similar unphysical effects in the simulations of Beresnyak (2011, 2012, 2014). In this case, the correlation properties of the fluctuations can be affected as well. In particular, the angular alignment of magnetic and velocity fluctuations can weaken. This is indeed consistent with Figure. 4 which illustrates the scaling of the alignment angle between the velocity and magnetic fluctuations measured at scale r (see the details of the measurement procedure in (Perez et al. 2012)). In the resolved run (dashed line) the alignment is well preserved down to the scale $r \sim 0.005$, corresponding to the scaling $-3/2$ observed in Figure. 1. In contrast, in the unresolved runs (solid and dash-dotted lines), the alignment is already significantly spoiled at scale $r \sim 0.05$, which is consistent with the transition to the $-5/3$ scaling at smaller scales (cf. Figure. 3).

In conclusion, we have demonstrated that the Kolmogorov first self-similarity hypothesis (1) does not apply to MHD turbulence. In contrast with the hydrodynamic case, the Fourier energy spectrum is not a universal function of the wavenumber normalized by the dissipation scale, $k\eta_s$. This happens due to the mediation of the small-scale turbulent energy cascade by the large-

scale magnetic field, which introduces the large-scale dependence in both the inertial and the dissipation intervals. We have proposed that the lack of universality has implications for numerical simulations of MHD turbulence. In particular, when the explicit physical dissipation is not strong in the vicinity of the numerical cutoff, the measured spectrum gets distorted by the numerical effects. The solution of the discrete numerical scheme in the cutoff vicinity has a Reynolds number scaling that is different from the scaling of the physical solution. This imposes stringent conditions on the numerical resolution required for correct simulations of MHD turbulence. The cutoff scale should decrease faster than the dissipation scale as the Reynolds number increases, in order for the numerical simulations to be adequately resolved.

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